

**2** **2.1** В цепи потенциалы ноль.

$$W_1 = \varphi_1 q' = \frac{kq q'}{r_1} \quad W_2 = \varphi_2 q' = \frac{kq q'}{r_2}$$

$$A_{12} = W_1 - W_2 = \frac{kq q'}{4\pi\epsilon_0} \left( \frac{1}{r_1} - \frac{1}{r_2} \right)$$

В случае  $\delta$ ),  $A=0$ , т.к.  $r_1=r_2$ .

**2.2**



$$\varphi_0 = 2 \sum_{n=1}^{\infty} \frac{k(-1)^n q}{\alpha a} = \frac{2kq}{\alpha} \sum_{n=1}^{\infty} \frac{(-1)^n}{\alpha}$$

$$= -\frac{q}{2\pi\epsilon_0 \alpha} \ln 2.$$

**2.3** а)  $\varphi_0^{(1)} = \frac{kq}{a/2} \quad \varphi_0^{(2)} = -\frac{kq}{a/2} \Rightarrow \varphi_0 = \varphi_0^{(1)} + \varphi_0^{(2)} = 0$

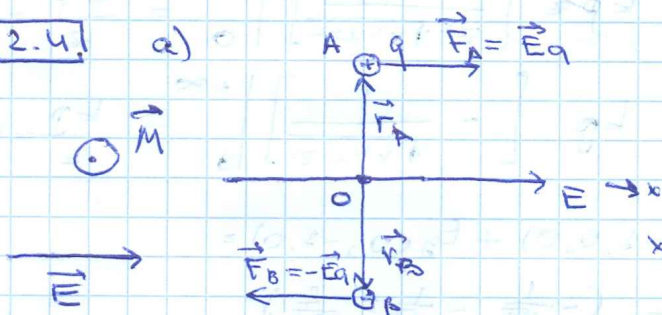
$\varphi_{\infty} = 0$

тогда  $A = q'(\varphi_0 - \varphi_{\infty}) = 0.$

б)  $\varphi_0^{(1)} = \varphi_0^{(2)} = \frac{kq}{a/2} \quad \varphi_0 = \frac{kq}{a} \quad \varphi_{\infty} = 0$

$A = q'(\varphi_0 - \varphi_{\infty}) = +\frac{kq q'}{a}.$

**2.4** а)



$W = q(\varphi_A - \varphi_B) =$

$$= q \int_A^B \vec{E} d\vec{r} = -q \vec{E} \vec{r} = 0.$$

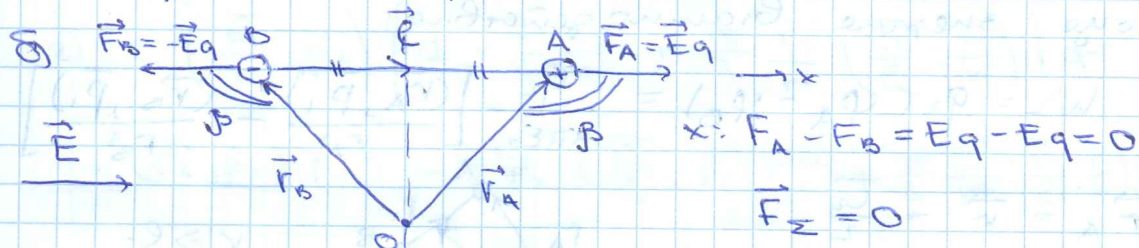
х:  $F_A - F_B = Eq - Eq = 0.$

$\vec{F}_{\Sigma} = 0$

$$\vec{M} = [\vec{r}_A \times \vec{F}_A] + [\vec{r}_B \times \vec{F}_B] = [\vec{r}_A \times \vec{E}q] + [\vec{r}_A \times \vec{E}q] =$$

$$= 2[\vec{r}_A \times \vec{E}q] = [2\vec{r}_A \times \vec{E}] \quad (\text{направление на вал})$$

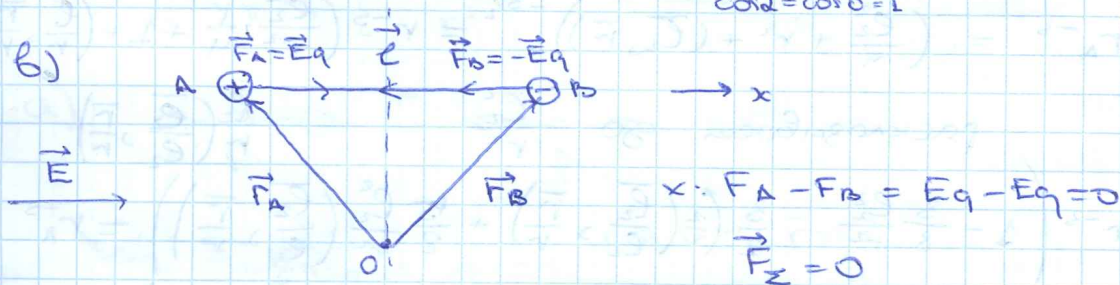
$$M = p_e E \sin \frac{\pi}{2} = p_e E \quad (2\vec{r}_A = \vec{e})$$



$$\vec{M} = [\vec{r}_A \times \vec{F}_A] + [\vec{r}_B \times \vec{F}_B] = [\vec{r}_A - \vec{r}_B, \vec{F}_A] = 0$$

$$W = q(\varphi_A - \varphi_B) = q \int_A^B \vec{E} d\vec{r} = -q \vec{E} \vec{e} = -E p_e$$

$\cos \alpha = \cos 0 = 1$



$$\vec{M} = [\vec{r}_A \times \vec{F}_A] + [\vec{r}_B \times \vec{F}_B] = [\vec{r}_A - \vec{r}_B, \vec{F}_A] = 0$$

$$W = q(\varphi_A - \varphi_B) = q \int_A^B \vec{E} d\vec{r} = -q \vec{E} \vec{e} = E p_e$$

$\cos \alpha = \cos \pi = -1$

2.5 Потенциал гравитации в  $\tau$  M (1-й порядок)

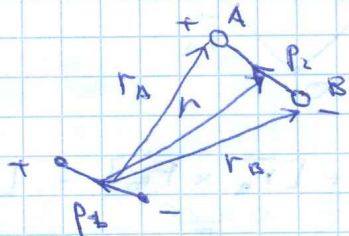
$$\varphi(M) = \frac{(\vec{r}, \vec{p}_e)}{4\pi\epsilon_0 \cdot r^3}$$

Тогда энергия взаимодействия:

$$W_L = q_2(\varphi_A - \varphi_B) = \frac{q_2}{4\pi\epsilon_0} \left[ \frac{(\vec{r}_A, \vec{p}_1)}{r_A^3} - \frac{(\vec{r}_B, \vec{p}_1)}{r_B^3} \right]$$

$$\vec{r}_A = \vec{r} + \frac{\vec{e}_2}{2}$$

$$\vec{r}_B = \vec{r} + \frac{\vec{e}_2}{2}$$



$r \gg e_2$

$$r_A^2 = \left( \frac{\vec{e}_2}{2} + \vec{r} \right)^2 = \frac{e_2^2}{4} + r^2 + (\vec{e}_2, \vec{r})$$

$$r_A^{-3} = \left( \frac{e_2^2}{4} + r^2 + (\vec{e}_2, \vec{r}) \right)^{-3/2} = r^{-3} \left( \frac{e_2^2}{r^2} \cdot \frac{1}{4} + 1 + \left( \frac{\vec{e}_2}{r}, \frac{\vec{r}}{r} \right) \right)^{-3/2}$$

разносимое по  $\frac{e_2^2}{r^2}$

$$\frac{e_2}{r} \left( \frac{\vec{e}_2}{e_2}, \frac{\vec{r}}{r} \right)$$

$$= r^{-3} \left( 1 - \frac{3}{8} \frac{e_2^2}{r^2} - \frac{3}{2} \frac{e_2}{r} \left( \frac{\vec{e}_2}{e_2}, \frac{\vec{r}}{r} \right) + \frac{15}{8} \frac{e_2^2}{r^2} \left( \frac{\vec{e}_2}{e_2}, \frac{\vec{r}}{r} \right) \right) = r_A^{-3}$$

$$r^{-3} \left( 1 - \frac{3}{8} \frac{e_2^2}{r^2} + \frac{3}{2} \frac{e_2}{r} \left( \frac{\vec{e}_2}{e_2}, \frac{\vec{r}}{r} \right) + \frac{15}{8} \frac{e_2^2}{r^2} \left( \frac{\vec{e}_2}{e_2}, \frac{\vec{r}}{r} \right) \right) = r_B^{-3}$$

$$(\vec{r}_A, \vec{p}_1) = (\vec{r}, \vec{p}_1) + \left( \frac{\vec{e}_2}{2}, \vec{p}_1 \right)$$

$$(\vec{r}_B, \vec{p}_1) = (\vec{r}, \vec{p}_1) - \left( \frac{\vec{e}_2}{2}, \vec{p}_1 \right)$$

$$1) (\vec{r}, \vec{p}_1) \left[ -3 \frac{e_2}{r} \left( \frac{\vec{e}_2}{e_2}, \frac{\vec{r}}{r} \right) \right] r^{-3} = -3 \frac{e_2}{r} \frac{(\vec{r}, \vec{p}_1) \left( \frac{\vec{e}_2}{e_2}, \frac{\vec{r}}{r} \right)}{r^3} =$$

$$= \frac{-3 (\vec{r}, \vec{p}_1) (\vec{e}_2, \vec{r})}{r^5}$$

$$2) 2 \left( \frac{\vec{e}_2}{2}, \vec{p}_1 \right) \left[ 1 - \frac{3}{8} \frac{e_2^2}{r^2} + \frac{15}{8} \frac{e_2^2}{r^2} \left( \frac{\vec{e}_2}{e_2}, \frac{\vec{r}}{r} \right) \right] r^{-3} =$$

$$= (\vec{e}_2, \vec{p}_1) r^{-3} - \frac{3 e_2^3}{8 r^3} \left( \frac{\vec{e}_2}{e_2}, \vec{p}_1 \right) r^{-2} + \frac{15}{8} \frac{e_2^3}{r^3} \left( \frac{\vec{e}_2}{e_2}, \frac{\vec{r}}{r} \right) (\vec{e}_2, \vec{p}_1) r^{-2}$$

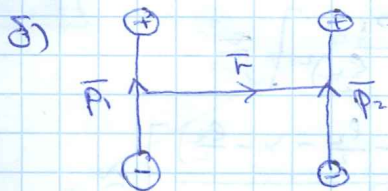
$$\approx (\vec{e}_2, \vec{p}_1) r^{-3}$$

$$W_2 = \frac{q_2}{4\pi\epsilon_0} \frac{(\vec{e}_2, \vec{p}_1)}{r^3} + \frac{q_2}{4\pi\epsilon_0} \frac{-3(\vec{r}, \vec{p}_1)(\vec{r}, \vec{e}_2)}{r^5} =$$

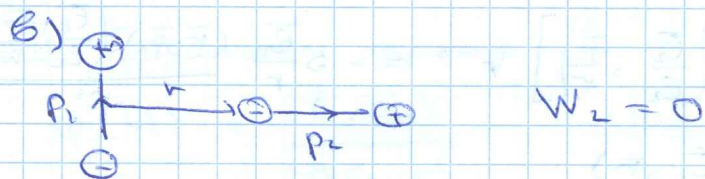
$$= \frac{1}{4\pi\epsilon_0} \left[ \frac{\vec{p}_1 \cdot \vec{p}_2}{r^3} - 3 \frac{(\vec{r}, \vec{p}_1)(\vec{r}, \vec{p}_2)}{r^5} \right]$$



$$W_2 = -\frac{p_1 p_2}{2\pi\epsilon_0 r^3} \quad r \gg e_1, r \gg e_2$$



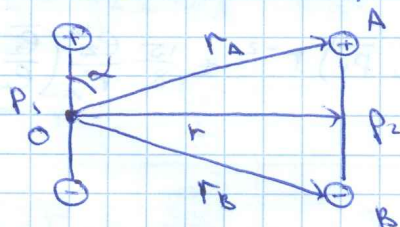
$$W_2 = \frac{1}{4\pi\epsilon_0} \frac{p_1 p_2}{r^3}$$



2-ой членов

8)

$$r_0 = \sqrt{r^2 + \frac{p_2^2}{4}} \approx r$$



$$W_2 = q_2 (\varphi_A - \varphi_B) =$$

$$= \frac{q_2}{4\pi\epsilon_0} \left( \frac{r_A p_1}{r_A^3} - \frac{r_B p_1}{r_B^3} \right) =$$

$$= [r_A = r_B = r_0] \cdot \frac{1}{2}$$

$$\stackrel{1}{=} \frac{q_2}{4\pi\epsilon_0} \left[ \frac{r_0 p_1 \cos \alpha}{r_0^3} - \frac{r_0 p_1 \cos(\pi - \alpha)}{r_0^3} \right] =$$

$$= \frac{q_2}{4\pi\epsilon_0} \left[ \frac{2 r_0 p_1 \cos \alpha}{r_0^3} \right] = \frac{p_1 p_2}{4\pi\epsilon_0 r_0^3} \approx \frac{p_1 p_2}{4\pi\epsilon_0 r^3}$$

$$\stackrel{2}{=} \frac{q_2}{4\pi\epsilon_0 r_0^3} \overline{p_1 p_2} = \frac{p_1 p_2}{4\pi\epsilon_0 r_0^3} \approx \frac{p_1 p_2}{4\pi\epsilon_0 r^3}$$

а)

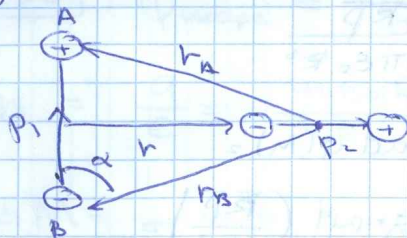


$$W_2 = \frac{q_2}{4\pi\epsilon_0} \left[ -\frac{p_1}{(x - \frac{p_2}{2})^2} + \frac{p_1}{(x + \frac{p_2}{2})^2} \right] \approx$$

$$= \frac{q_2 p_1}{4\pi\epsilon_0} \left[ \frac{(x + \frac{p_2}{2} + x - \frac{p_2}{2})(x - \frac{p_2}{2} - x - \frac{p_2}{2})}{(x^2 - \frac{p_2^2}{4})^2} \right] \approx$$

$$\approx \frac{q_2 p_1}{4\pi\epsilon_0} \frac{2x \cdot (-p_2)}{x^4} \approx -\frac{p_1 p_2}{2\pi\epsilon_0 x^3}$$

6)



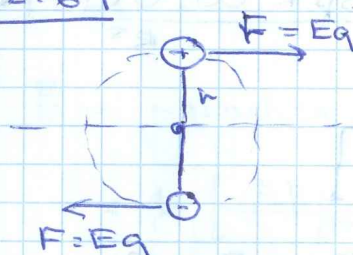
$$W_1 = q_1 (\varphi_A - \varphi_B) =$$

$$= \frac{q_1}{4\pi\epsilon_0} \left( \frac{\vec{r}_A \cdot \vec{P}_2}{r_A^3} - \frac{\vec{r}_B \cdot \vec{P}_2}{r_B^3} \right) =$$

$$= [r_A = r_B = r_0] =$$

$$= \frac{q_1}{4\pi\epsilon_0 \cdot r_0^3} \vec{P}_2 \cdot (\vec{r}_A - \vec{r}_B) = \frac{\vec{P}_1 \cdot \vec{P}_2}{4\pi\epsilon_0 r_0^3} = 0.$$

2.6



$$J = m r^2 + m r^2 = 2 m r^2, \quad r = \frac{\ell}{2}$$

$$J_E = 2 F r$$

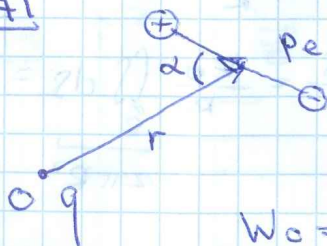
$$E = \frac{2 E q r}{2 m r^2} = \frac{E q \frac{\ell}{2}}{m \frac{\ell^2}{4}} = \frac{2 E p_e}{m \ell^2} = J$$

из задачи 2.4 получ. (БСЭ)

$$0 = \frac{J \omega^2}{2} - E p_e \quad ; \quad p_e = q \ell = 2 q r$$

$$\omega = \sqrt{\frac{2 E p_e}{J}} = \frac{2}{\ell} \sqrt{\frac{p_e E}{m}}$$

2.7



$$W = \varphi(0) q = q \frac{(-\vec{r} \cdot \vec{p}_e)}{4\pi\epsilon_0 r^3} =$$

$$\alpha \in [0, \pi] \quad = \frac{-q r p_e \cos \alpha}{4\pi\epsilon_0 r^3}$$

$$W_0 = 0 = \frac{-q r p_e \cos \alpha}{4\pi\epsilon_0 r^3} \Rightarrow \cos \alpha = 0 \Rightarrow \alpha = \frac{\pi}{2}$$

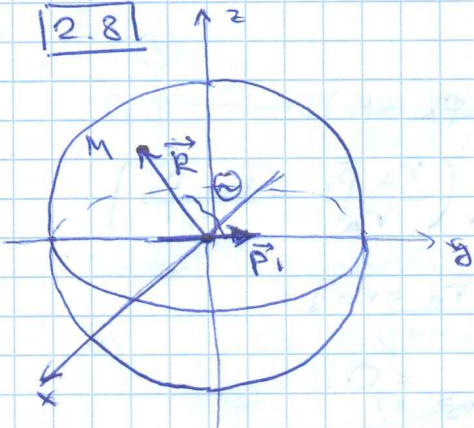
$$W' = \frac{q r p_e}{4\pi\epsilon_0 r^3} (+\sin \alpha)$$



$$W_{\min} \sim \alpha = 0$$

$$W_{\max} \sim \alpha = \pi.$$

2.8



$$\varphi(M) = \frac{R\bar{p}}{4\pi\epsilon_0 R^3}$$

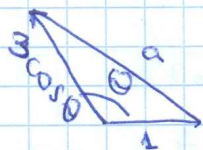
$$\vec{E} = -\text{grad } \varphi(M) =$$

$$= -k \text{grad} \left( \frac{R\bar{p}}{R^3} \right) =$$

$$= k \left[ \frac{3(\bar{p}\bar{R})\bar{R}}{R^5} - \frac{\bar{p}}{R^3} \right] =$$

$$= k \left[ \frac{3pR \cos \theta \bar{R}}{R^5} - \frac{R^2 \bar{p}}{R^5} \right] = k \left[ \frac{3pR^2 \cos \theta \bar{e}_1 - pR^2 \bar{e}_2}{R^5} \right]$$

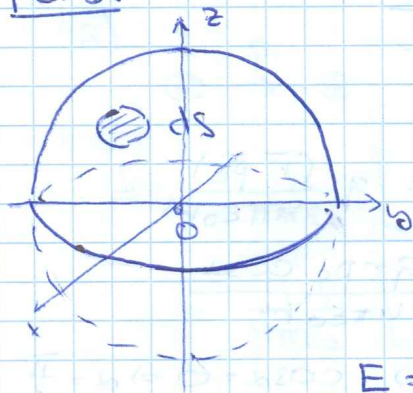
$$= \frac{p}{4\pi\epsilon_0} \frac{1}{R^3} [3 \cos \theta \bar{e}_1 - \bar{e}_2]$$



$$1 + 3 \cos^2 \theta - 6 \cos \theta \cos \theta = a^2$$

$$E = \frac{p}{4\pi\epsilon_0 R^3} \sqrt{1 + 3 \cos^2 \theta}$$

2.3



$$dq = \sigma ds$$

$$d\varphi = \frac{k dq}{R} = \frac{k \sigma ds}{R}$$

$$\varphi = \iint_S k \sigma \frac{ds}{R} = \frac{k \sigma}{R} \underbrace{\iint_S ds}_{2\pi R^2} = \frac{R \sigma}{2\epsilon_0}$$

$$E = -\text{grad } \varphi$$

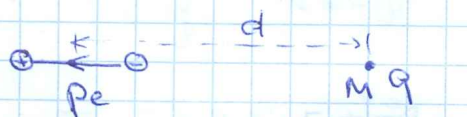
permanente gaece

2.10  $\rho_{\text{surface}} = \frac{1}{4\pi\epsilon_0} \frac{q}{R}$

$n = \frac{q}{e} = \frac{4\pi\epsilon_0 R}{e} = 2 \cdot 10^{10}$

$\Delta M = m \cdot n = 2 \cdot 10^{-20} \text{ кг}$

2.11

  $\varphi(M) = \frac{\vec{r} \cdot \vec{P}}{4\pi\epsilon_0 d^3}$

$\vec{E} = -\text{grad}\varphi = k \left[ \frac{3(\vec{r} \cdot \vec{r})\vec{r}}{d^5} - \frac{\vec{P}}{d^3} \right] =$   
 $= k \left[ -\frac{3pd^2}{d^5} - \frac{\vec{P}}{d^3} \right]$

$E = k \left[ -\frac{3pd^2}{d^5} + \frac{p}{d^3} \right] = -\frac{kqp}{d^3} = -\frac{P}{2\pi\epsilon_0 d^3}$

$|F| = |Eq| = \frac{qP}{2\pi\epsilon_0 d^3}$

$|F| = \frac{qP}{2\pi\epsilon_0 d^3}$

В центре

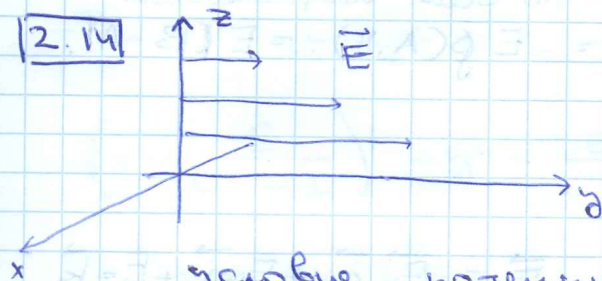


q притяжение



q отталкивание

2.14



$\vec{E} = (0, F(z), 0)$

$F(z) = \alpha z + \beta, \alpha \neq 0$

горизонтальное поле

$\text{rot } \vec{E} = 0$

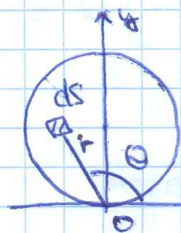
$$r_0 + \vec{E} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & F(z) & 0 \end{vmatrix} = \vec{i} [0 - F'_z(z)] + \vec{j} 0 + \vec{k} 0$$

$$= -F'_z(z) \vec{i}$$

$$F'_z = (\alpha z + \beta)' = \alpha \neq 0$$

$\Rightarrow$  поле неоднородное  $\Rightarrow$  не консервативное.

2.15



$$r = [2R \sin \theta], \quad \theta \in [0, \pi]$$

$$dq = \sigma ds \quad dq = \frac{k \sigma ds}{r}$$

$$\varphi = \frac{\sigma}{4\pi\epsilon_0} \oint_S \frac{ds}{r} = \frac{\sigma}{4\pi\epsilon_0} \int_0^\pi d\theta \int_0^{2R \sin \theta} \frac{1}{r} r dr =$$

$$= \frac{\sigma}{4\pi\epsilon_0} \int_0^\pi 2R \sin \theta d\theta = \frac{2R\sigma}{4\pi\epsilon_0} \int_0^\pi \sin \theta d\theta =$$

$$= \frac{R\sigma}{2\pi\epsilon_0} [-\cos \theta] \Big|_0^\pi = \frac{R\sigma}{\pi\epsilon_0}$$

2.12

Если напряженность, то поле  $\vec{E}$  однородное, но в любом направлении

$$\varphi_A - \varphi_B = \int_A^B \vec{E} d\vec{r} = E \int_A^B (A, B) = E |B - A|.$$

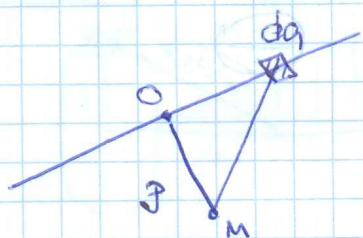
тогда

$$E_x = \frac{\varphi_1 - \varphi_2}{a}$$

$$E_y = \frac{\varphi_1 - \varphi_2}{a}, \quad \vec{E} = E_x \vec{i} + E_y \vec{j} + E_z \vec{k}$$

$$E_z = \frac{\varphi_1 - \varphi_3}{a}$$

2.13



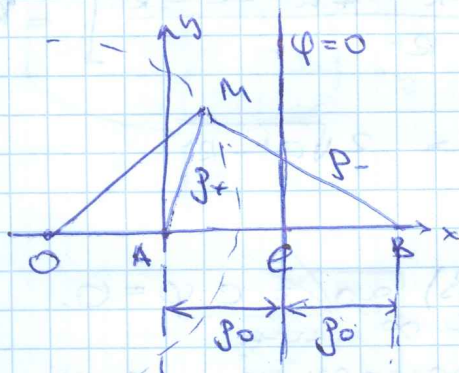
$$dq = dx$$

$$d\varphi = \frac{k dq}{r} = \frac{k dx}{\sqrt{x^2 + p^2}}$$

$$\varphi_+ = 2 \int_p^{p_0} k \frac{dx}{\sqrt{x^2 + p^2}} = 2k \left[ \ln(\sqrt{x^2 + p^2} + x) \right]_p^{p_0} =$$

$$= 2k \ln \frac{p_0}{p_+}$$

$$\varphi_- = -2k \ln \frac{p_0}{p_-}$$



площадь между проводниками  
интервал  $2p_0$

$p_0$  — расстояние от плоскости  
до проводников

$$\varphi(M) = \varphi_+ + \varphi_- = 2k \ln \frac{p_-}{p_+}$$

$$p_+ = \sqrt{x^2 + y^2}$$

$$p_- = \sqrt{(x-e)^2 + y^2}$$

$$\frac{p_-}{p_+} = \sqrt{\frac{(x-e)^2 + y^2}{x^2 + y^2}} = \text{const} = c$$

$$x^2 - 2xe + e^2 + y^2 = e^2 x^2 + e^2 y^2$$

$$x^2 + y^2 + 2 \frac{e}{c^2 - 1} x = \frac{e^2}{c^2 - 1}$$

$$\left( x + \frac{e}{c^2 - 1} \right)^2 + y^2 = \frac{e^2}{c^2 - 1} + \frac{e^2}{(c^2 - 1)^2} = \frac{e^2 c^2}{(c^2 - 1)^2} = R^2$$

— окружность с центром  $\left( -\frac{e}{c^2 - 1}, 0 \right)$

и радиусом  $R = \left| \frac{ce}{c^2 - 1} \right| \Rightarrow \text{цилиндр}$

$$\begin{cases} e + \frac{2e}{e^2 - 1} = e \frac{e^2 + 1}{e^2 - 1} = 2a \\ e \frac{e}{e^2 - 1} = R \quad (2) \end{cases}$$



$$\frac{e^2 + 1}{e} = \frac{2a}{R}$$

$$e^2 - 2 \frac{a}{R} e + 1 = 0$$

$$e = \frac{a}{R} + \sqrt{\frac{a^2}{R^2} - 1} = \frac{a + \sqrt{a^2 - R^2}}{R} \Rightarrow (2)$$

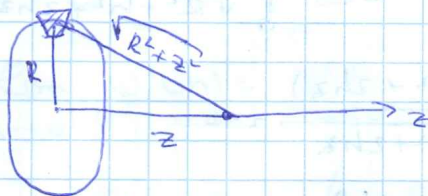
$$e \frac{a + \sqrt{a^2 - R^2}}{R} \left[ \frac{a^2 + 2a\sqrt{a^2 - R^2} + a^2 - R^2 - R^2}{R^2} \right]^{-1} = R$$

$$e = \frac{2a^2 + 2a\sqrt{a^2 - R^2} - 2R^2}{a + \sqrt{a^2 - R^2}} = 2\sqrt{a^2 - R^2}$$

\*  $\rho_0$  - расстояние от  $A(B)$  до  $\tau$  с  $\varphi = 0$ .  
 можно положить  $\rho_0 = \infty$  или  
 заметить, что плоскость посередине между  
 проводниками с паралл. т.т. имеет  $\varphi = 0$ .

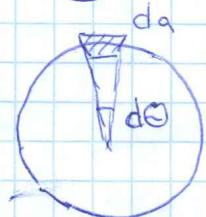
2.9

1) нагнати норушчан карые 6 торке  
на 0cu 1 норушчан карые

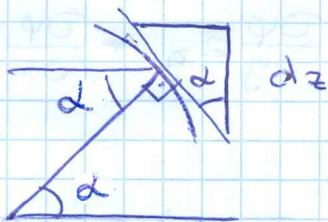
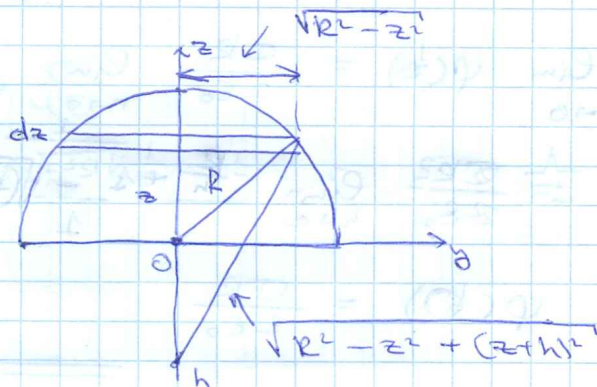
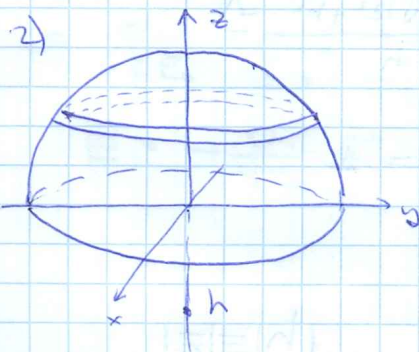


$$dq = \frac{Q}{2\pi} d\theta$$

$$d\varphi = \frac{k dq}{\sqrt{R^2 + z^2}} = \frac{k \frac{Q}{2\pi} d\theta}{\sqrt{R^2 + z^2}}$$



$$\varphi = \int_0^{2\pi} d\varphi = \frac{k Q}{2\pi} \cdot \frac{1}{\sqrt{R^2 + z^2}} \int_0^{2\pi} d\theta = \frac{k Q}{\sqrt{R^2 + z^2}}$$



$$\cos \alpha = \frac{\sqrt{R^2 - z^2}}{R}$$

$$Q \equiv dq = \sigma dS; \quad dS = 2\pi \sqrt{R^2 - z^2} dz \frac{1}{\cos \alpha} =$$

$$= 2\pi \sqrt{R^2 - z^2} \frac{R}{\sqrt{R^2 - z^2}} dz = 2\pi R dz$$

$$d\varphi = \frac{k dq}{r} = 2\pi \sigma R k \cdot \frac{dz}{\sqrt{R^2 - z^2 + (z+h)^2}}$$

$$\begin{aligned}
 \varphi(h) &= \frac{\sigma R}{2\epsilon_0} \int_0^R \frac{dz}{\sqrt{R^2 - z^2 + (z+h)^2}} = \frac{\sigma R}{2\epsilon_0} \int_0^R \frac{dz}{\sqrt{R^2 + h^2 + 2hz}} = \\
 &= \frac{\sigma R}{2\epsilon_0} \cdot \frac{1}{+2h} \int_0^R \frac{d(R^2 + h^2 + 2hz)}{\sqrt{R^2 + h^2 + 2hz}} = \\
 &= \frac{\sigma R}{2\epsilon_0} \cdot \frac{1}{2h} \left[ 2 \sqrt{R^2 + h^2 + 2hz} \right] \Big|_0^R = \\
 &= \frac{\sigma R}{2\epsilon_0} \cdot \frac{1}{h} \left[ R+h - \sqrt{R^2 + h^2} \right]
 \end{aligned}$$

$$\begin{aligned}
 \lim_{h \rightarrow 0} \varphi(h) &= \frac{\sigma R}{2\epsilon_0} \lim_{h \rightarrow 0} \frac{R+h - \sqrt{R^2 + h^2}}{h} \stackrel{1}{=} \\
 &\stackrel{1}{=} \frac{\sigma R}{2\epsilon_0} \lim_{h \rightarrow 0} \frac{1 - \frac{1}{2} \frac{2h}{\sqrt{R^2 + h^2}} \cdot 2h}{1} = 1
 \end{aligned}$$

$$\varphi(0) = \frac{\sigma R}{2\epsilon_0}$$

$$\underline{\underline{h \equiv z}}$$

$$\vec{E} = -\text{grad} \varphi = -\frac{\partial \varphi}{\partial z} \vec{e}_z - \frac{\partial \varphi}{\partial y} \vec{e}_y - \frac{\partial \varphi}{\partial x} \vec{e}_x;$$

$$\frac{\partial \varphi}{\partial y} = 0 \quad \frac{\partial \varphi}{\partial x} = 0$$

$$\begin{aligned}
 \frac{\partial \varphi}{\partial z} &= \frac{\partial}{\partial z} \left( \frac{\sigma R}{2\epsilon_0} \frac{R+z - \sqrt{R^2 + z^2}}{z} \right) = \\
 &= \frac{\sigma R}{2\epsilon_0} \cdot \frac{\left( 1 - \frac{zh}{\sqrt{R^2 + h^2}} \right) h - \left( R+h - \sqrt{R^2 + h^2} \right)}{h^2} =
 \end{aligned}$$

$$= \frac{\sigma R}{2\epsilon_0} \cdot \frac{1}{h^2} \left[ h - \frac{h^2}{\sqrt{R^2 + h^2}} - R - h + \sqrt{R^2 + h^2} \right] =$$

$$= \frac{\sigma R}{2\epsilon_0} \frac{1}{h^2} \left[ -R + \frac{R^2 + h^2 - h^2}{\sqrt{R^2 + h^2}} \right]$$

$$\lim_{h \rightarrow 0} \varphi'(h) = \frac{\sigma R}{2\epsilon_0} \lim_{h \rightarrow 0} \left( \frac{-R}{h^2} + \frac{R^2}{\sqrt{R^2 + h^2} \cdot h^2} \right) = \left\{ t = \frac{h}{R} \right\}$$

$$= \frac{\sigma R}{2\epsilon_0} \lim_{t \rightarrow 0} \left( \frac{-R + \frac{R^2}{R\sqrt{1-t^2}}}{R^2 t^2} \right) =$$

$$= \frac{\sigma R}{2\epsilon_0} \lim_{t \rightarrow 0} \left( \frac{-R + R \left[ 1 + t^2 \cdot \frac{1}{2} \right]}{R^2 t^2} \right) =$$

$$= \frac{\sigma}{2\epsilon_0} \lim_{t \rightarrow 0} \frac{+\frac{1}{2}t^2}{t^2} = +\frac{\sigma}{4\epsilon_0}$$

$$\Rightarrow \vec{\Pi} = -\frac{\sigma}{4\epsilon_0} \vec{e}_z$$